

Euclid Quick Data Release (Q1)

The Strong Lensing Discovery Engine D – Double-source-plane lens candidates

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ABSTRACT

Strong gravitational lensing systems with multiple source planes are powerful tools for probing the density profiles and dark matter substructure of the galaxies. The ratio of Einstein radii is related to the dark energy equation of state through the cosmological scaling factor β . However, galaxy-scale double-source-plane lenses (DSPLs) are extremely rare. In this paper, we report the discovery of four new galaxy-scale double-source-plane lens candidates in the Euclid Quick Release 1 (Q1) data. These systems were initially identified through a combination of machine learning lens-finding models and subsequent visual inspection from citizens and experts. We apply the widely-used LensPop lens forecasting model to predict that the full *Euclid* survey will discover 1700 DSPLs, which scales to 6 ± 3 DSPLs in 63 deg^2 , the area of Q1. The number of discoveries in this work is broadly consistent with this forecast. We present lens models for each DSPL and infer their β values. Our initial Q1 sample demonstrates the promise of *Euclid* to discover such rare objects.

Key words. Gravitational lensing: strong – Galaxies: halos – dark matter

1. Introduction

Strong gravitational lensing occurs when a background source and a foreground massive object align along our line of sight, resulting in the light from the source being split into multiple images or forming an Einstein ring (Einstein 1936; Zwicky 1937a,b). Sometimes there can be multiple sources at different redshifts behind the same lens galaxy, forming Einstein rings at different radii. Such systems are referred to as compound lenses or double-source-plane lenses (DSPLs).

In strong lensing systems, the radius of the Einstein ring, known as the Einstein radius (parameterised by θ_E), depends on both the mass profile of the lens and the cosmological distances involved. Performing lens modelling on systems with a single Einstein ring can constrain the local logarithmic density slope in the region where the strongly lensed images are observed, assuming a specific parametric form for the total mass profile of the lens galaxy (e.g., Suyu & Halkola 2010; Birrer & Amara 2018; Nightingale et al. 2021; Galan et al. 2022a). However, there are systematics affecting the results, such as the mass-sheet degeneracy (Falco et al. 1985; Schneider & Sluse 2013): by adding a constant mass sheet and rescale the convergence, mass-sheet transformations (MST) can alter the shape of the galaxy mass profile and rescaling the size of the source while keeping all lensing observables unchanged. In DSPL systems, adding an extra source plane can break the mass-sheet degeneracy of the lens if the mass contribution of the first source is neglected (Bradač et al. 2004) and the cosmology is known.

The presence of two rings at different radii makes DSPLs powerful tools for probing the mass distribution of galaxies, thereby constraining the properties of dark matter. The second ring provides an additional aperture within which the total mass is well-constrained, so one can disentangle the distribution of dark and luminous matter in the lens without additional kinematic data (Sonnenfeld et al. 2012). If a dark matter subhalo exists in the lens plane, the inclusion of a second source probes the

mass distribution on a larger radius. This can break degeneracies in the lens model and improve the constraints on its mass properties (see Figure 6 in Enzi et al. 2024, where the posteriors of the dark matter subhalo when modelled with two arcs are tighter). For example, several observations and analyses of the ‘Jackpot’ lens SDSS J0946+1006 have suggested the existence of an over-concentrated subhalo (see Vegetti et al. 2010; Minor et al. 2021; Ballard et al. 2024; Despali et al. 2024; Enzi et al. 2024).

DSPLs have also been used to constrain the equation of state of dark energy. For a system with multiple sources at different redshifts, the ratio of their Einstein radii is related to cosmological parameters, such as the dark energy equation of state (parameterised by w), through the cosmology scaling factor β . The cosmological measurements derived from DSPLs are independent of the Hubble constant and complement other cosmological measurements, as demonstrated by previous studies (see e.g., Gavazzi et al. 2008; Collett et al. 2012; Johnson et al. 2025). Collett & Auger (2014) shows that a single galaxy-scale DSPL system can provide competitive cosmological constraints assuming a power-law mass profile of the lens galaxy. Although cluster-scale lenses typically have multiple source planes and are also capable of measuring cosmological parameters (e.g., Soucail et al. 2004; Jullo et al. 2010; Caminha et al. 2016; Acebron et al. 2017; Magana et al. 2018; Caminha et al. 2022), their complex mass distributions limit the precision. While selecting strong lensing clusters or galaxy groups with simpler mass distributions is a possible alternative (Bolamperti et al. 2024), galaxy-scale lenses generally exhibit less systematic uncertainty due to their inherently simpler mass profiles. However, Schneider (2014) argues that there exists an analogue of the MST for DSPL systems, which can render the cosmological constraints significantly less restrictive. A 1 percent bias in β can give rise to a bias in w of approximately 0.3. Additional data from stellar kinematics, for example, can help break this degeneracy; however, achieving competitive results requires unbiased measurements of kinematics and correct assumptions about the mass profiles – both of which are challenging.

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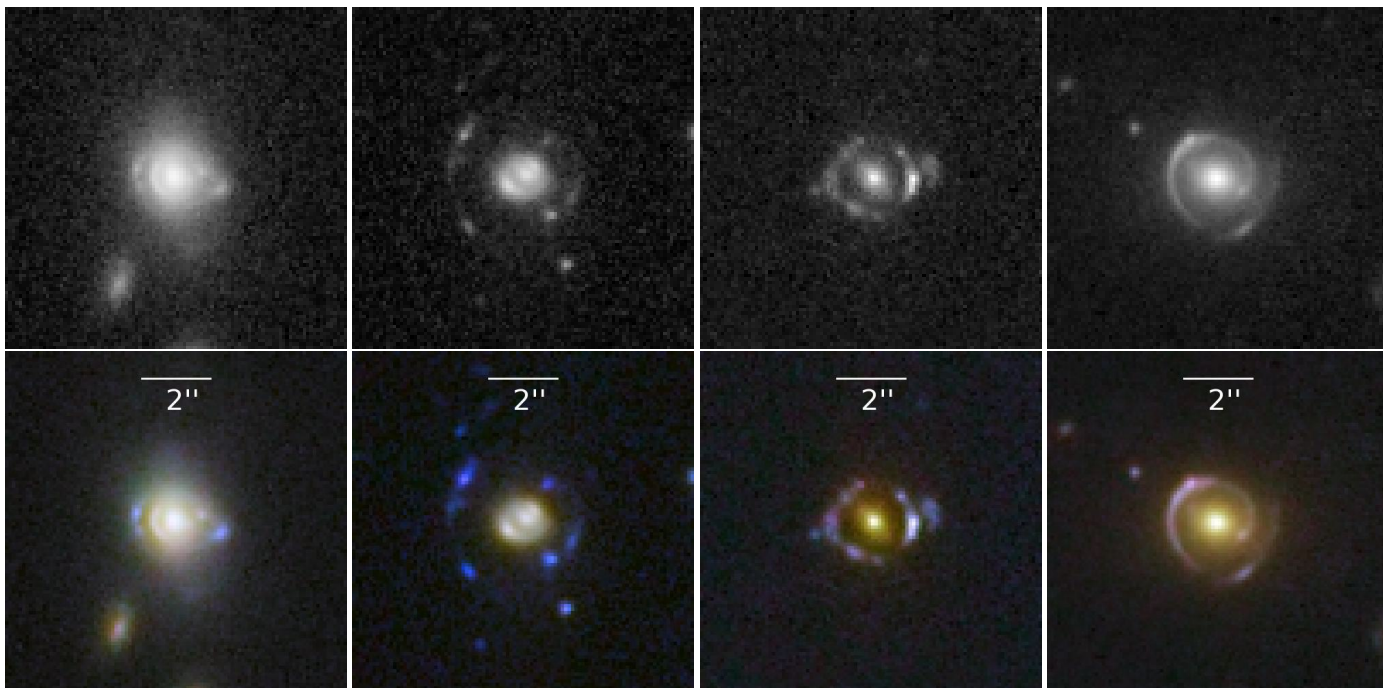


Fig. 1. I_E (top panels) and I_E - Y_E - J_E coloured images (bottom panels) of the DSPL candidates. From left to right there are the Teapot Lens, Cosmic Dartboard, Galileo's Lens, and Cosmic Ammonite, respectively. Orientation: north is up, and east is to the left.

Table 1. Sky locations are RA and Dec of the four lens systems

Name	RA	Dec
Teapot Lens	273.595°	67.138°
Cosmic Dartboard	59.565°	-50.948°
Galileo's Lens	66.685°	-48.111°
Cosmic Ammonite	61.239°	-49.373°

Unfortunately, galaxy-scale strong lenses with multiple background sources are exceedingly rare, with only a handful of known examples in the literature: the ‘Jackpot’ lens (Gavazzi et al. 2008); the ‘Eye of Horus’ (Tanaka et al. 2016); and J1721+8842 (Dux et al. 2024). Other DSPLs which the sources have similar Einstein radii are: DES0408–5354 (Lin et al. 2017); and the ‘Cosmic horseshoe’ (Belokurov et al. 2007). This rarity arises from the fact that whilst the probability of being a single plane lens scales as θ_E^2 , the probability of lensing two sources scales as θ_E^4 . Even with the depth and resolution of the *Hubble* Space Telescope, only about one in a hundred lenses are expected to be DSPL (Gavazzi et al. 2008), although the exact rate depends on the depth, resolution, and wavelength of the observations (Collett et al. 2012). With the *Euclid* space telescope providing an unprecedented inspection of the sky, forecasts show that around 1700 DSPLs will be discovered during the survey (rescaling from the 170 000 single-source-plane lenses forecast in Collett 2015).

Here we report the discovery of four new galaxy-scale DSPL candidates in the 63 deg² of Euclid Quick Release 1 (Q1 Euclid Quick Release Q1 2025). The I_E -band images and coloured images of the four systems are presented in Fig. 1, and their coordinates are shown in Table 1. Based on the morphology of the four discovered lens systems, they have been named the ‘Teapot Lens’, ‘Cosmic Dartboard’, ‘Galileo’s Lens’ (this lensing con-

figuration somewhat resembles Galileo’s hand-drawn depiction of Saturn), and ‘Cosmic Ammonite’.

The discovery of these four new DSPLs were made using the Strong Lensing Discovery Engine, a structured workflow that integrates machine learning (ML) with citizen science classifications, followed by expert grading. This paper is part of a series of papers, with Euclid Collaboration: Walmsley et al. (2025) describing the *Euclid* lens finding engine and new discoveries. Euclid Collaboration: Rojas et al. (2025) describes our effort to build a suitable training sample for Q1 and the lens search with high-velocity dispersion galaxies. Euclid Collaboration: Lines et al. (2025) explains the ML models used to find the strong lenses. Finally Euclid Collaboration: Holloway et al. (2025) introduces an ensemble classifier combining the citizen science and the different ML classifiers.

The paper is organised as follows. In Sect. 2, we briefly summarise the *Euclid* survey and the lens-finding methods employed. Section 3 introduces the lens modelling algorithm, followed by the lens models and spectra presented in Sect. 4. In Sect. 5 we present the forecast of the number of DSPLs that *Euclid* will discover in its planned survey area. Finally, Sect. 6 presents our conclusions. We discuss the limitations of our lens-finding approach and provide examples of typical false DSPL systems in Appendix. A.

2. *Euclid* double-source-plane lens search

The search for DSPLs is a by-product of the Strong Lensing Discovery Engine, which had a primary goal of finding single-source-plane galaxy-scale strong lenses in *Euclid* data. In the lens-finding pipeline described in Euclid Collaboration: Walmsley et al. (2025), the lens candidates selected by machine learning and citizen scientists (from objects that are brighter than 22.5 in I_E in the 63 deg² of Q1) are sent to the Galaxy Judges project, where a group of strong lensing experts provide a final grade for each lens candidate. Following this semi-automated search for

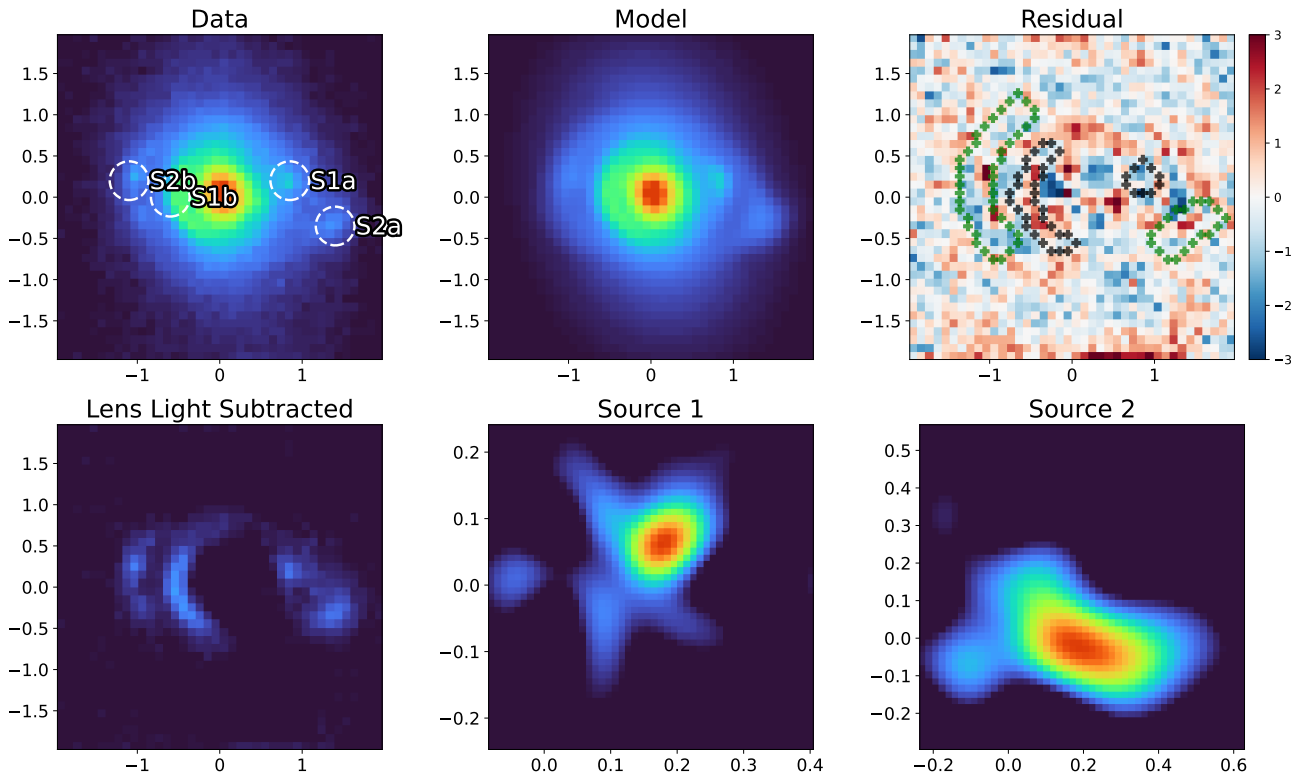


Fig. 2. Lens model of the Teapot Lens. I_E band image, lens model, and the residual respectively. The bottom panels display the lens light-subtracted image and two source models. The inner pair of arcs are labelled as S1a and S1b, while the outer pair of arcs are labelled as S2a and S2b. In the residual plot, the black and green scatter points represent the edges of the masks for the inner and outer arcs, respectively. The axis tick marks are in arcseconds.

all galaxy-galaxy lenses, a group of (approximately 10) experienced experts re-inspected the top 10 000 lenses, and identified four DSPLs by eye. All four of our DSPL candidates are ranked in the top 250 lenses by the expert visual inspection.

The primary criterion for identifying a DSPL system is the presence of two pairs of arcs at different Einstein radii. The colours of the arcs serve as a key indicator to determine whether they originate from the same source plane. Once a lens is identified as a potential DSPL candidate, preliminary lens modelling (described in Sect. 3) is performed to further evaluate the plausibility of its configuration.

Euclid offers significant advantages for DSPL searches due to its high resolution imaging over a large area, with its point-spread function (PSF) having a full width at half maximum of approximately $0''.16$ in the I_E band (Euclid Collaboration: Mellier et al. 2024; Euclid Collaboration: McCracken et al. 2025). This high resolution enables the separation of lens light from the arcs and allows multiple arcs to be resolved. Although the infrared channels have a much lower resolution, their colour information is helpful for associating different arcs.

3. Double-source-plane lens modelling

3.1. Background theory

For a lensed image at position θ , the scaled deflection angle of a galaxy $\alpha(\theta)$ is related to its lensing potential ψ via

$$\alpha(\theta) = \nabla\psi(\theta), \quad (1)$$

and the relation between lensing potential and lensing convergence is

$$\kappa(\theta) = \frac{1}{2} \nabla^2 \psi(\theta), \quad (2)$$

where convergence is defined as,

$$\kappa(\theta) \equiv \frac{\Sigma(\theta)}{\Sigma_{\text{cr}}}. \quad (3)$$

The convergence is the surface mass density normalised by the critical lensing surface density

$$\Sigma_{\text{cr}} \equiv \frac{c^2 D_s}{4\pi G D_l D_{ls}}, \quad (4)$$

where D is the angular diameter distance between two objects, and the subscripts ‘l’ and ‘s’ denote the lens galaxy and the source galaxy, respectively.

In a DSPL system, the lens equation of the first source plane can be written as

$$\theta_1 = \theta - \beta \alpha_1(\theta), \quad (5)$$

where α_1 is the reduced deflection angle of the first source at the image position θ , and θ_1 is the position of the first source on its source plane. Here, β is the cosmological scaling factor which is the ratio of the angular diameter distances between the different redshift planes:

$$\beta = \frac{D_{ls1} D_{s2}}{D_{s1} D_{ls2}}, \quad (6)$$

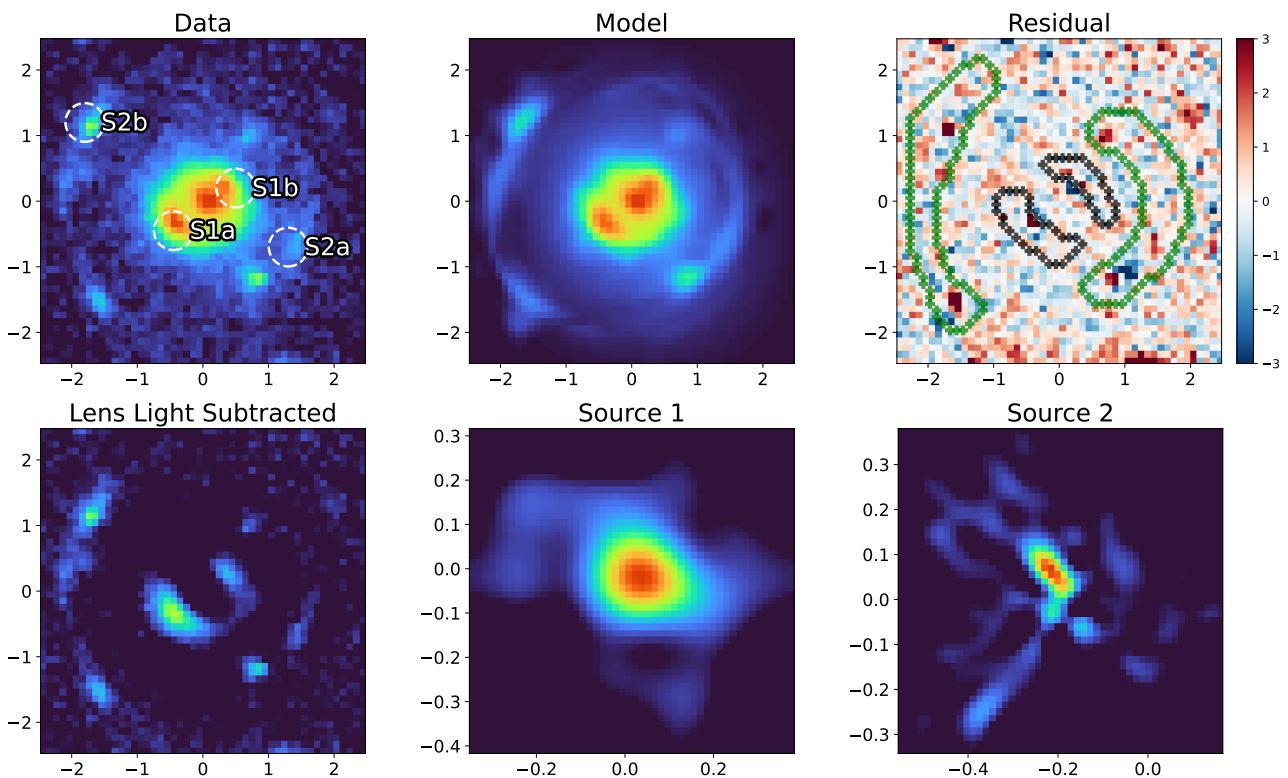


Fig. 3. Same as Fig. 2, but for the Cosmic Dartboard.

where the subscripts ‘s1’ and ‘s2’ denote source 1 and source 2, respectively. The lens equation of the second source plane is then:

$$\theta_2 = \theta - \alpha_1(\theta) - \alpha_{s1}[\theta - \beta \alpha_1(\theta)], \quad (7)$$

where θ_2 is the position of the second source on its source plane and α_{s1} is the deflection angle of the mass on the first source plane. In a simple case where we assume the lens galaxy has a singular isothermal sphere (SIS) profile, the parameter β is just the ratio of the two Einstein radii (the geometry of the DSPL is in Figure 1 of Collett & Auger 2014).

The lenses are modelled using an elliptical power-law (EPL) mass model with an external shear component. The convergence (κ_{EPL}) of the EPL model can be parameterised as

$$\kappa_{\text{EPL}}(\rho, \gamma, q) = \frac{3 - \gamma}{2} \left(\frac{\theta_E}{\rho} \right)^{\gamma-1}, \quad (8)$$

where $\rho^2 = x^2 + y^2/q$ is the squared elliptical radius and q is the axis ratio, γ is the power-law index of the density slope, and θ_E is the Einstein radius corresponding to source 2. The cosmological parameters can therefore be measured by relating β from lens modelling and the redshifts of the system.

3.2. Lens modelling strategy

We use the open-source lens modelling code *Herculens*¹ (Galan et al. 2022b) in combination with a multiplane extension. *Herculens* is based on the automatic differentiation and compilation features of JAX² and can run on graphics processing units (GPUs). The detailed description of the extension can

¹ <https://github.com/Herculens/herculens>

² <https://docs.jax.dev/en/latest/>

be found in Enzi et al. (2024). We note here that our lens modelling is primarily aiming to validate the plausibility of these systems being DSPLs, and not to precisely infer the parameters of these systems. The lack of redshift information for either the lens or the sources prevents us from building robust mass distribution and leverage the full statistical analyses from Markov chain Monte Carlo (MCMC) methods. However, our lens modelling is fully capable of recovering the source-plane morphology of the galaxies in order to confirm the double-source-plane nature of the systems. Here we briefly summarise the modelling strategy.

The data used for modelling comes from the I_E band because it has the highest pixel resolution ($0''.1 \text{ pixel}^{-1}$). We measure the root mean square of the background pixels and infer the shot noise from the modelled lens light. The PSF is derived from the *Euclid* pipeline. Since the *Euclid* I_E band spans a wide wavelength range (550–900 nm), the PSF profile will be influenced by the spectral energy distribution of the target. Consequently, lensed arcs with markedly different colours might exhibit different PSFs, which might introduce additional uncertainties into the lens model.

We use *Numpyro*'s implementation of stochastic variational inference (SVI; see Wingate & Weber 2013). We employ the AdaBelief optimiser (Zhuang et al. 2020) with a low-rank multivariate normal distribution as the guiding probability distribution. This guiding distribution is not complex enough to accurately recover the full posterior distribution, but it is computationally much cheaper than MCMC methods because it can use the auto-differentiable nature of JAX (Bradbury et al. 2018). The inference was done through optimising the guiding distribution to minimise the Kullback–Leibler divergence to the true posterior rather than sampling over the posterior.

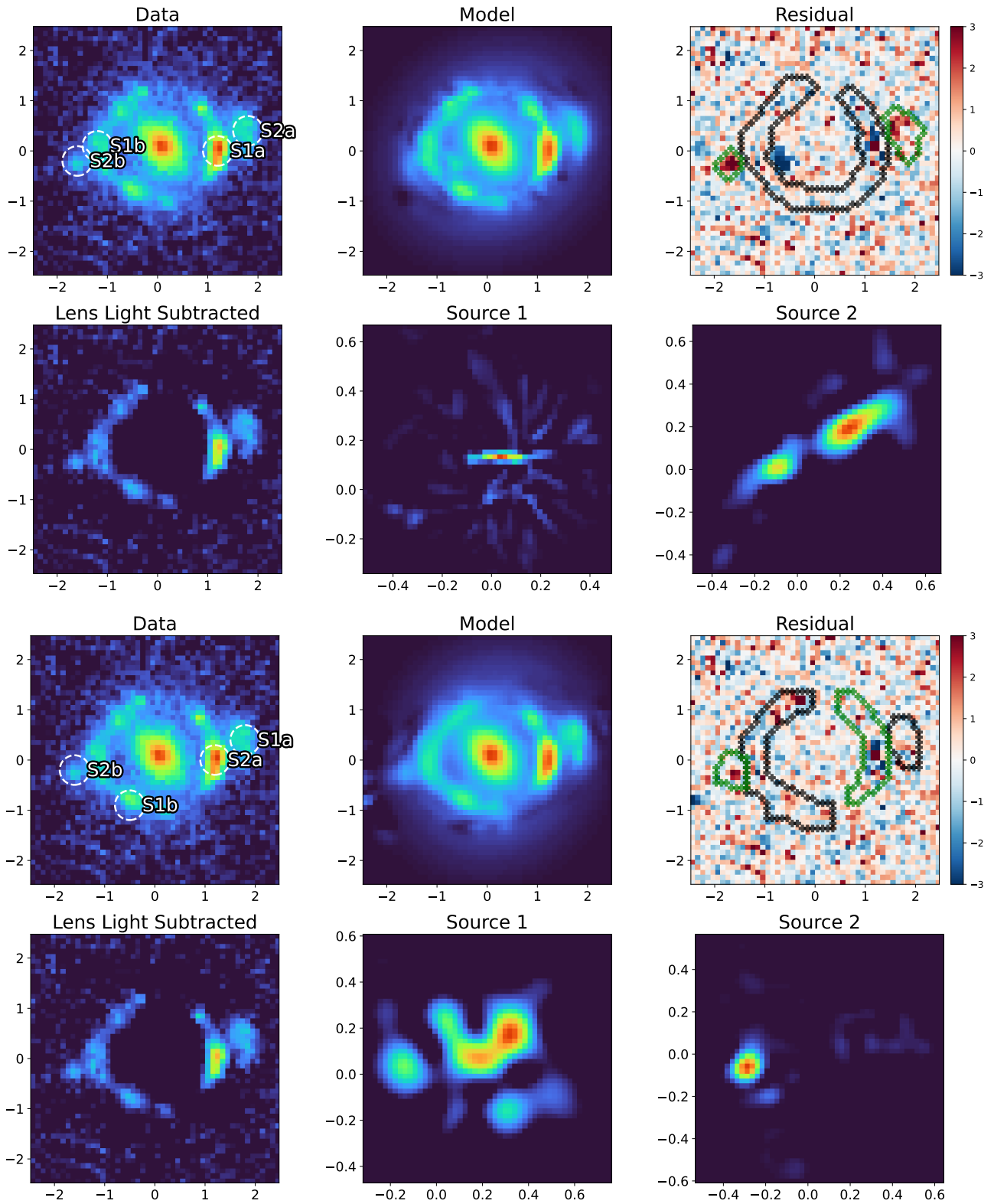


Fig. 4. Same as Fig. 2 but for Galileo's Lens. The top six figures are the lens modelled with a single source plane. The bottom six figures are the lens modelled with double-source-planes.

Since the inner arcs of our DSPL candidates are mixed with the lens light, we model the lens light simultaneously with the arcs. In our model, the lens light is modelled with the sum of five elliptical Gaussian luminosity profiles with flexible centres (Shajib 2019; He et al. 2024; Enzi et al. 2024). The sources are first

modelled with a single elliptical Gaussian luminosity profile to provide an approximate answer. Then we use the parameterised lens model as the starting point and describe the sources as fields that vary on regularly pixelated grids. We compute each pixel's field value by multiplying the Matérn power spectrum (see Stein

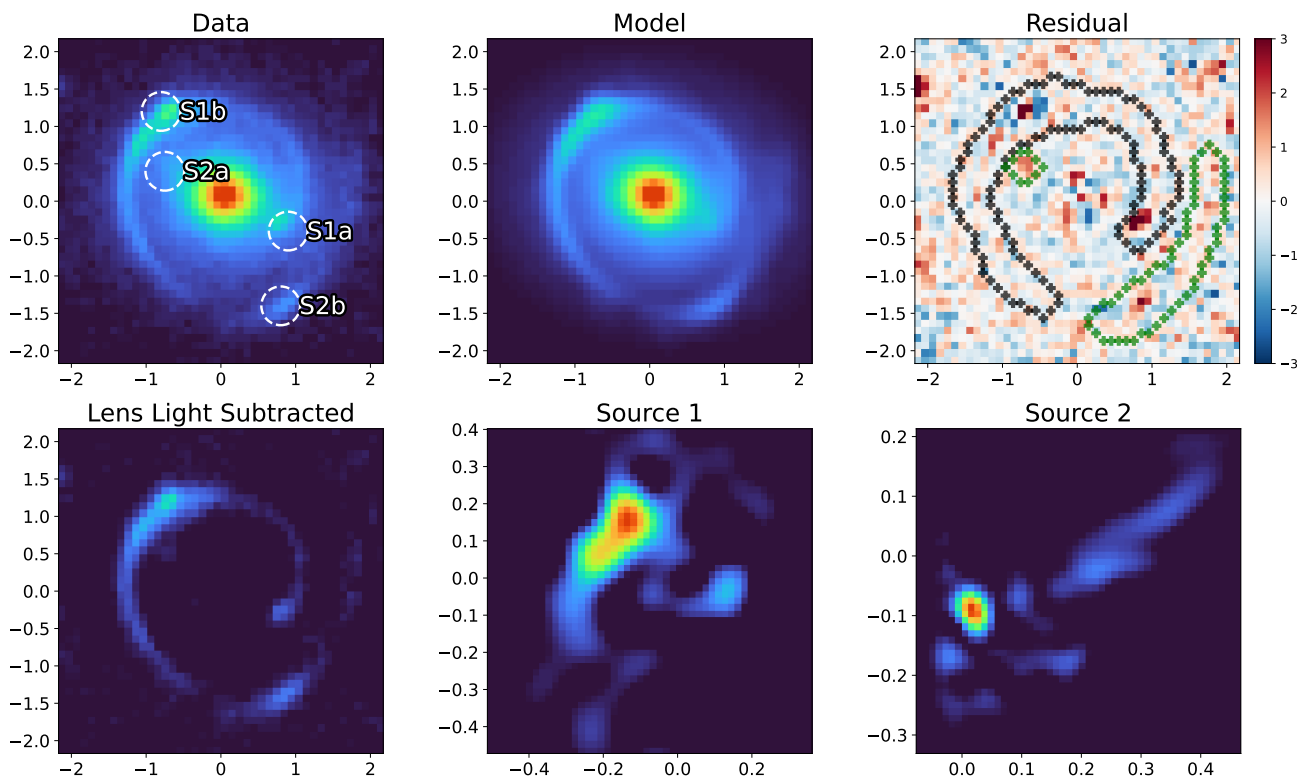


Fig. 5. Same as Fig. 2, but for Cosmic Ammonite.

2012) with white noise (sampled from a standard normal distribution) and then applying the inverse Fourier transform to the result. A flat prior has been applied to every mass model parameter.

For each of our targets, we run 20 000 iterations in 10 SVIs. Each SVI realisation has different random initialisations, and we pick the SVI result with the smallest average loss value to be our lens model. The lens model results are shown in Table 2. We do not show the uncertainty of the lens model because SVI tends to underestimate the lens model uncertainty. Uncertainties from the following MCMCs are typically to be around 0.05 for each parameter between the 10 SVI runs.

4. Lens model of DSPL candidates

In this section, we present and analyse the lens models of our DSPL candidates (Teapot Lens, Cosmic Dartboard, Galileo’s Lens, and Cosmic Ammonite). We also present one system that we initially thought was a DSPL candidate, the ‘Crackpot’, which was found to be better modelled with two sources on a single plane (Sect 4.5). Since the Crackpot is not a DSPL lens, it is not shown in Table 2.

4.1. The Teapot Lens

This lens was discovered during the visual inspection of the top 20 000 ranked lenses according to the lens-finding version of the machine-learning model Zoobot (see Euclid Collaboration: Lines et al. 2025). It ranked 2349 by Zoobot and 43 in Galaxy Judges. It was classified as a ‘Grade A’ lens. The system features two concentric rings at distinct Einstein radii, each with a different colour, making it a highly promising DSPL candidate.

The lens model of Teapot Lens is presented in Fig. 2. The lens light-subtracted image reveals a distinct pair of inner rings. The lens model results indicate an inner ring at $0^{\prime}62$ and a β of 0.74, leaving a clean residual within the arc’s position. The positive residual near the centre could be due to multiple reasons: dust lanes or AGN in the lens galaxy; PSF mismatch impacting the lens light subtraction; a satellite galaxy located close to the primary lens; or an inner ‘zig-zag’ image of the second source (Collett & Bacon 2016).

4.2. Cosmic Dartboard

This lens was discovered during the visual inspection of the top 20 000 ranked lenses. It ranked 1902 by Zoobot and 94 in Galaxy Judges. It was classified as a ‘Grade A’ lens. The lens model of Cosmic Dartboard is presented in Fig. 3. Our lens model successfully recovered all the details in the image. However, due to limited resolution, it is challenging to perfectly disentangle the lens light from the inner arc. The outer arc reconstruction could be significantly improved with higher signal-to-noise ratio data.

The inner ring of this lens was inferred to be at $0^{\prime}45$, while the β value is 0.51. The first source is massive according to the result from the lens model ($\theta_{\text{sis1}} = 0^{\prime}48$) because it appears to be an elliptical galaxy. If spectroscopic redshifts are obtained, the large Einstein radius ratio should provide valuable insights for cosmological measurements as the image configuration suggests $z_{s1} \ll z_{s2}$, which would provide the optical lever arm for constraining dark energy (Collett et al. 2012).

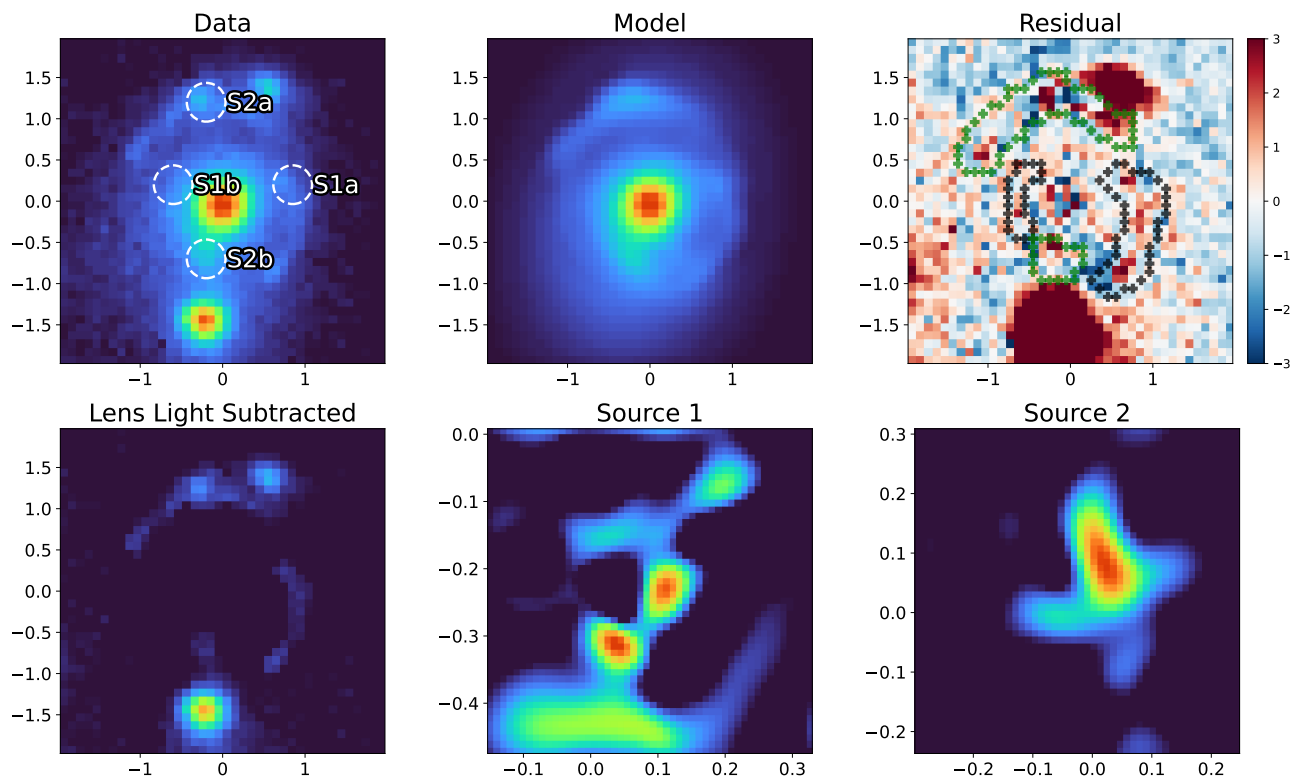


Fig. 6. Same as Fig. 2. But for the CrackPot lens.

4.3. Galileo's Lens

This lens was first discovered in Space Warps and Galaxy Judges, it ranked 3 by Zoobot (though it was missed as a DSPL candidate in the first pass of Zoobot by TC, TL and NL) and 19 in Galaxy Judges. It was classified as a 'Grade A' lens. This system was proposed as a DSPL system because it features a central ring structure and two faint arcs on the outskirts. However, the apparent inner ring has an unusual configuration and the colours of all the arcs are similar, making it difficult to classify confidently. It is also difficult to explain both the very elliptical central lens light and the nearly circular ring merely by classifying it as a ring galaxy.

Here, we present two lens models. The first model assumes a DSPL configuration, while the second model considers a lens with two sources situated on the same redshift plane. Neither model can explain the lensing configuration really well. It is possible that this system is a single ring system where the two blue objects nearby are just field galaxies. Spectroscopic data or imaging with higher resolution should provide definitive evidence to decide whether this system is indeed a DSPL.

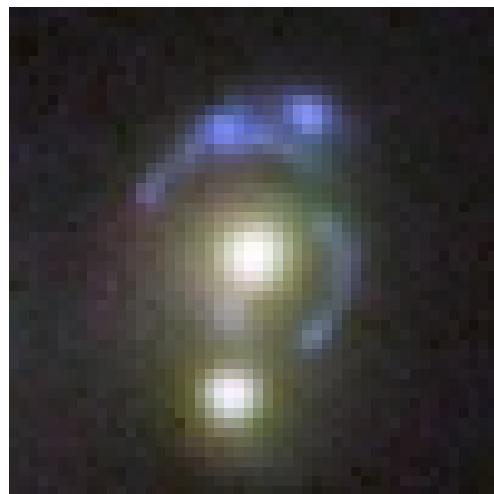


Fig. 7. The colour image of the Crackpot lens.

4.4. Cosmic Ammonite

This lens was discovered during the visual inspection of the top 1000 Galaxy Judges candidates. It ranked 7 in Zoobot (but was initially assumed to be a multicomponent single source plane system) and 207 in Galaxy Judges. It was classified as a 'Grade B' lens, but the expert scores were not unanimous, with 4 A* votes (lens with special interest), 1 A, 3 B, and 2 X (non-lens).

The lens model of Cosmic Ammonite is presented in Fig. 5. Our lens model successfully recovered all the details in the image. The β of this system is constrained to be around 0.85. Although this system was modelled with excellent fidelity and is

almost certainly a DSPL, it received a surprisingly low score in Galaxy Judges. The best explanation is that the lensing configuration of this system is uncommon, so human experts are less confident about this object. We initially modelled this system expecting to rule it out as a DSPL, with the two sources on a single plane, however the modelling result shows that this is a confident DSPL with $\beta \approx 0.85$. This demonstrates the power of lens modelling over human experts in identifying DSPLs with β not much smaller than 1.

Table 2. Properties and lens model parameters of the four systems. We show the lensed I_E -band magnitudes of the lens, source 1 (s1), and source 2 (s2). The lens model parameters are the best solutions after 10 SVI runs per lens. Uncertainties are typically around 0.05 for each parameter between the 10 SVI runs.

Name	$m_{ab}(\text{lens}) (I_E)$	$m_{ab}(s1) (I_E)$	$m_{ab}(s2) (I_E)$	β	θ_{E1}	θ_{sis1}	θ_{E2}	γ	ϕ	q
Teapot Lens	20.0	23.3	24.0	0.74	0''.62	0''.13	0''.89	1.83	-0.44	0.63
Cosmic Dartboard	21.2	22.9	23.2	0.51	0''.45	0''.48	1''.31	1.63	-1.32	0.64
Galileo's Lens	22.3	22.7	24.4	0.69	1''.09	0''.28	1''.52	2.11	0.39	0.76
Cosmic Ammonite	20.0	22.3	24.2	0.85	1''.18	0''.15	1''.35	2.22	0.17	0.72

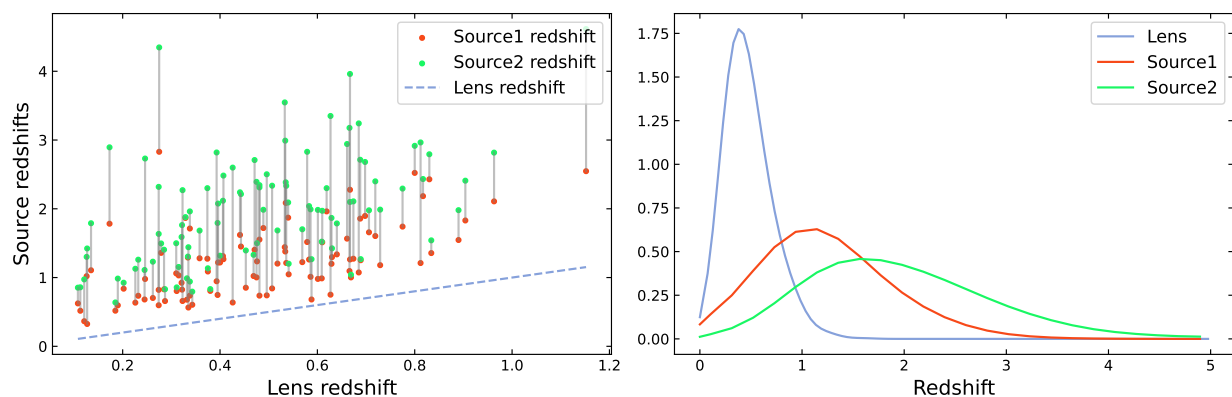


Fig. 8. *Left:* the redshift distribution of 100 example DSPLs from LensPop. *Right:* The histogram represents the redshift distribution of 1700 systems drawn from LensPop. The blue line indicates the lens redshift, while the red and green dashed lines mark the redshifts of source 1 and source 2, respectively.

4.5. The Crackpot: a single plane system with two sources

This lens was first discovered during visual inspection of high-velocity dispersion galaxies from Dark Energy Spectroscopic Instrument (Euclid Collaboration: Rojas et al. 2025) as part of the effort to build a training set for machine learning. It was later rediscovered in Space Warps and Galaxy Judges, ranking 622 in the Zoobot and 237 in Galaxy Judges. It was classified as a 'Grade B' lens. As shown in Fig. 7, the system features two blue arcs at different radii. It is a lens with two bright lensing elliptical galaxies. While the counter-image of the top arc is clearly visible at the bottom left of the lens, the counter-image of the inner arc is only faintly visible in the lens light-subtracted image, making its identification less convincing.

Figure 6 shows the lens model of the Crackpot lens. Assuming the faint inner arc is real, the double-source-plane lens model suggests that the two images have similar Einstein radii. However, the presence of a nearby galaxy at the bottom of the image complicates the mass profile. Based on these factors, we believe that this lens is unlikely to be a DSPL, but rather a lens with two sources at the same redshift. We have named this system the Crackpot as a tongue-in-cheek reference to the fact it is not a Jackpot lens after all.

5. Expected rate and population of DSPLs in Euclid

The Euclid survey should enable the construction of a sample of approximately 1700 galaxy-scale DSPL systems. This forecast is derived from the LensPop package (Collett 2015), modified to include multiple background sources (we neglect the mass of the first source). We also impose more stringent constraints than the LensPop defaults. Specifically, we require that both sources

have one or more arcs of length 0''.3 – this ensures a reasonable possibility that the density slope of the lens can be recovered from Euclid imaging alone. The redshift distribution for lenses and sources is shown in Fig. 8. Although most compound lenses are at $z \approx 0.5$, a significant fraction of lenses are at $z < 0.2$ and at $z > 1$, which is promising for a precise constraint on the mass distribution in lenses. Of the 1700 expected Euclid DSPLs, approximately 6 ± 3 should fall inside the Q1 footprint (assuming that the DSPLs are randomly distributed). The entire Euclid survey will cover about $14\,000 \text{ deg}^2$, whereas the Q1 footprint considered here spans only 63 deg^2 . The forecasted number of systems in such a small area is expected to be modest, so even a difference of a few lenses (e.g., finding four instead of the predicted six) can be attributed to small-number statistics. Poisson fluctuations and cosmic variance can easily shift the observed number by a few systems relative to theoretical forecasts.

Our four DSPLs already represent a more than doubling of the galaxy-galaxy DSPL population. They should be useful for cosmography, but without any redshift information, it is impossible to map β values onto cosmological parameter constraints. Notably, the Cosmic Dartboard has $\beta \approx 0.51$ which is quite rare based on the β distribution of the mock catalogue as shown in Fig. 9 (only 6% of the DSPLs have $\beta < 0.5$, so the probability of having at least one DSPL with $\beta < 0.5$ in four systems is 0.2). This indicates that our forecast might underestimate the DSPL population observed by Euclid. Theoretically, smaller β values (two source galaxies at very different redshift) are more sensitive to the cosmology parameters, since the DSPL with a decreased β provides enhanced geometric leverage and mitigates degeneracies amongst cosmological parameters. For instance, when $\beta \approx 1$ ($z_{s1} \approx z_{s2}$), variations in cosmological parameters can result in β remaining close 1.

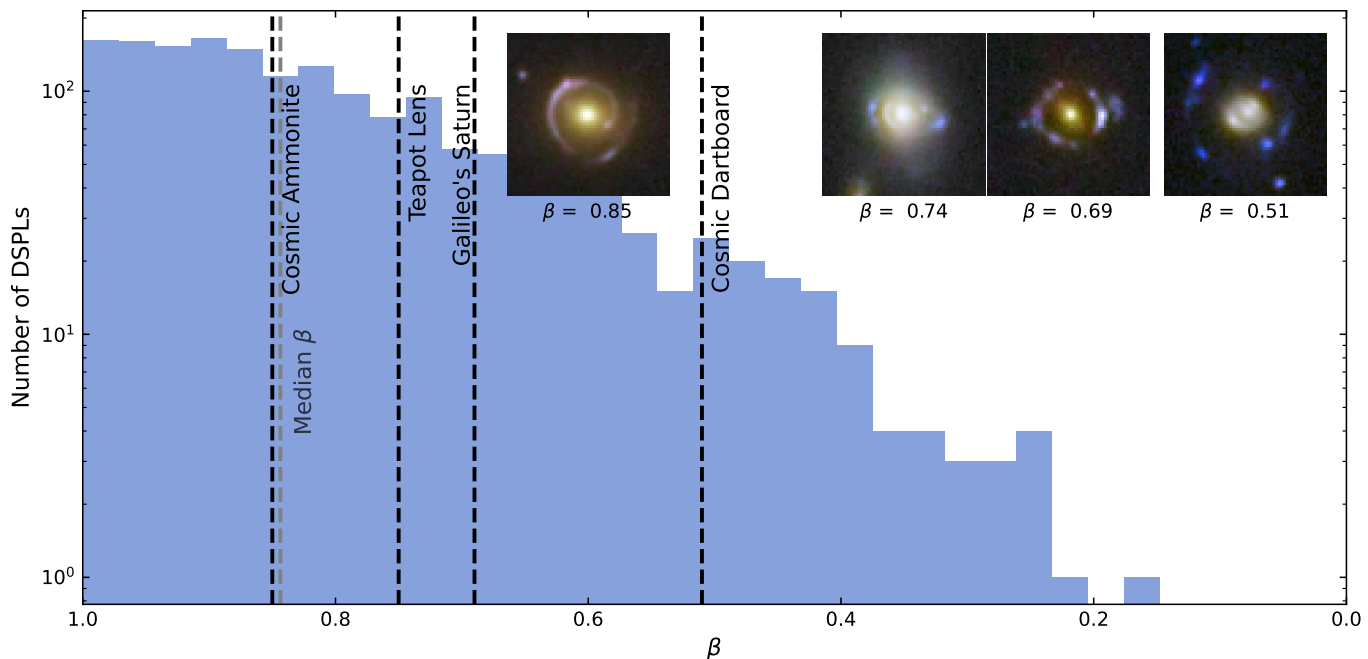


Fig. 9. Distribution of β from the forecast. The black dashed lines mark the measured β values for DSPLs discovered in Q1, and the gray dashed line indicates the median β value in the forecast catalogue.

6. Conclusions

We have identified four new galaxy-scale DSPL candidates in Q1, significantly extending the limited sample of known DSPL systems. Through detailed lens modelling, we strengthened the plausibility of their DSPL nature and derived the β (cosmological scaling factor which represents a distance ratio) parameters for each candidate, demonstrating their potential ability in cosmological studies. We also have a handful of tentative DSPL candidates for which higher-resolution imaging and spectroscopic redshifts are needed to make definitive conclusions.

We have piggybacked on the single source plane lens search to find interesting DSPL candidates. We did not train any machine or human classifiers to explicitly look for DSPLs. One consequence of not creating ML lens-finders trained on DSPLs is that they do not learn to value DSPL systems higher than regular lenses. This means the DSPLs will not necessarily be ranked exceptionally highly amongst the lenses, which was what was found in Q1 (Euclid Collaboration: Lines et al. 2025). Future *Euclid* single-plane-lens searches will be over larger areas, meaning we will be unable to visually inspect the same proportion of the total sample as we have done in Q1: scaling up the proportion of the total number of images visually inspected in Q1 to the full *Euclid* survey corresponds to visually inspecting 6 million images, which is likely intractable. Both the DSPLs and the single-source-plane lenses found in Q1 will likely enable significant improvement in the ML performance, and training ML models on DSPLs should increase the probability of these being recovered in future *Euclid* lens searches. However, it may be possible that a dedicated DSPL search will be needed for *Euclid* DR1 and beyond.

It is possible that some DSPLs remain to be found in Q1, either because they were ranked poorly by the single source plane lens ML classifiers or because they have been missed in visual inspection (we do not yet know how our methodology performs with small Einstein radius systems). We have also missed any

lenses that do not pass our initial lens cuts ($I_E < 22.5$ mag). Some lenses are expected to be faint in I_E ($I_E > 24$ mag, Collett 2015) although these would typically be low mass or high redshift lenses (e.g., lens redshift larger than 1.5). Either scenario is less likely to produce a *Euclid*-detectable DSPL than a galaxy that is more luminous in I_E . Our forecasts indicate that the full *Euclid* survey at the end of operations is expected to uncover 1700 DSPLs, whilst extrapolating up from our four DSPLs in 63 deg² yields 1000 (± 500) DSPLs in the full survey. Whether we ultimately find 1000 or 1700 lenses in the full *Euclid* data set, it is already clear that *Euclid* will revolutionise research using DSPLs.

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7. Data Availability

The Q1 data is available at the *Euclid* science archive. The forecast population of DSPLs are available at *LensPop* github repository. The derived data products are available upon request from the corresponding author.

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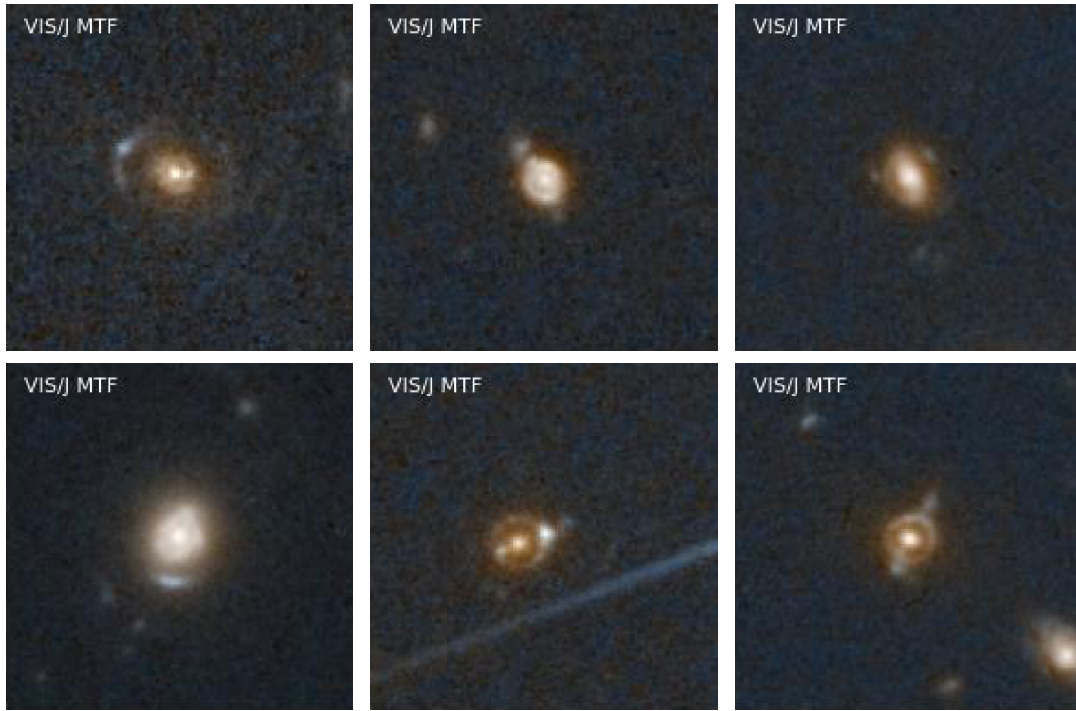


Fig. A.1. Low probability DSPL candidates selected among the top 1000 ranked galaxies in Galaxy Judges.



Fig. A.2. Candidate DSPL imposters selected among the top 1000 ranked galaxies in Galaxy Judges.

Appendix A: Other DSPL lens candidates

Due to the large survey area and high-resolution images provided by *Euclid*, rarer single-plane lensing configurations, and false positives can be discovered which could be misidentified as possible DSPL systems. Figure A.1 shows a sample of lens candidates in Q1 which might be DSPLs but we can not classify them with confidence due to their small Einstein radii. Figure A.2 shows a sample of images that could be confused for DSPLs but we believe are most likely contaminants. Here we outline several candidate configurations that create images that are similar to DSPLs:

- Double cusp configuration: When a source is positioned near a cusp of the tangential caustic, three closely spaced lensed images appear in the lens plane, while a fourth, more isolated and typically less magnified image, forms at a closer distance. If two sources within the same source plane are located near two opposing cusps of the diamond-shaped caustic, the resulting lensing configuration can produce a ring-like structure near the lens, along with two smaller arcs inside the ring. This configuration may resemble a DSPL system and could be mistakenly identified as such.
- Spiral galaxy and lens: In strong lensing systems where the deflector is a spiral galaxy, features like spiral arms or star-forming rings can sometimes be misidentified as secondary rings at different (smaller or larger) radii. This is because star-forming regions often exhibit a distinct blue colour, similar to that of background lensed sources. Such cases are not common, as face-on spiral galaxies typically have low projected surface mass density, resulting in a small lensing cross-section. However, at least two possible cases were found in our sample although they may not even be lenses. This type of lens has its unique value but it's beyond the scope of this paper.

- Spiral galaxy with multiple arms: As described above, spiral arms can resemble lensed arcs, making certain spiral galaxies appear similar to DSPL systems. This is particularly true when the central bulge of the galaxy is large enough to mimic the appearance of an elliptical galaxy. However, such systems can typically be easily ruled out through lens modelling.
- Elliptical lens with complex shells: In addition to spiral arms, the shell structures of elliptical galaxies can also resemble lensed arcs. These features become more apparent after subtracting the lens light in preliminary lens modelling ([Euclid Collaboration: Walmsley et al. 2025](#)). However, such structures are often noisy, as they are typically buried beneath the bright lens light, making them more challenging to identify without careful analysis.
- Lens system with nearby galaxies: galaxies located close in projection to a lens but outside the multiply imaged region can mimic an image from a doubly lensed system. An expert might incorrectly guess that there is an undetected counter-image of this galaxy close to the centre of the primary lens.

The scenarios described above represent the most common cases where DSPL systems can be misidentified. Conversely, a genuine DSPL system can also be misclassified as one of these cases. To make a definitive determination either lens modelling of higher angular resolution images or spectroscopic redshifts for each component, are required.