Euclid Quick Data Release (Q1)

The first catalogue of strong-lensing galaxy clusters

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ABSTRACT

We present the first catalogue of strong lensing galaxy clusters identified in the Euclid Quick Release 1 observations (covering 63.1 deg²). This catalogue is the result of the visual inspection of 1260 cluster fields. Each galaxy cluster was ranked with a probability, \mathcal{P}_{lens} , based on the number and plausibility of the identified strong lensing features. Specifically, we identified 83 gravitational lenses with $\mathcal{P}_{\text{lens}} > 0.5$, of which 14 have $\mathcal{P}_{\text{lens}} = 1$, and clearly exhibiting secure strong lensing features, such as giant tangential and radial arcs, and multiple images. Considering the measured number density of lensing galaxy clusters, approximately 0.3 deg⁻² for $\mathcal{P}_{\text{lens}} > 0.9$, we predict that *Euclid* will likely see more than 4500 strong lensing clusters over the course of the mission. Notably, only three of the identified cluster-scale lenses had been previously observed from space. Thus, Euclid has provided the first high-resolution imaging for the remaining 80 galaxy cluster lenses, including those with the highest probability. The identified strong lensing features will be used for training deep-learning models for identifying gravitational arcs and multiple images automatically in Euclid observations. This study confirms the huge potential of Euclid for finding new strong lensing clusters, enabling exciting new discoveries on the nature of dark matter and dark energy and the study of the high-redshift Universe.

Key words. Galaxies: clusters: general – Gravitational lensing: strong – cosmology: observations – dark matter

1. Introduction

Gravitational lensing in galaxy clusters is widely recognised as a powerful tool for determining their total mass distribution, including baryonic and dark components, across scales ranging from several kpc to Mpc. This can be achieved through strong lensing (e.g., Grillo et al. 2015; Mahler et al. 2018; Bergamini et al. 2023; Diego et al. 2023; Furtak et al. 2023; Acebron et al. 2024), weak lensing (e.g., Medezinski et al. 2016; Umetsu et al. 2020), or combined analyses (e.g., Jauzac et al. 2016; Liesenborgs et al. 2020; Niemiec et al. 2023). These methods also allow for the measurement of key cosmological parameters that govern cosmic geometry and the expansion rate (e.g., Jullo et al. 2010; Caminha et al. 2016, 2022; Magaña et al. 2018; Grillo et al. 2024), as well as the detailed study of the intrinsic properties of background lensed galaxies (e.g., Coe et al. 2013; Bouwens et al. 2014; Hashimoto et al. 2018; Meštrić et al. 2022; Vanzella et al. 2024).

Unfortunately, strong-lensing galaxy clusters are relatively rare (Oguri 2010), underscoring the critical role of wide-field surveys in building statistical samples. High-resolution optical and near-infrared imaging is particularly effective for identifying strong-lensing features with precision and reliability. However, such observations are typically constrained by small fields of view, often limited to a few arcminutes. This restriction has likely contributed to the relatively small number of studies leveraging high-resolution, space-based observations to significantly expand samples of strong-lensing galaxy clusters (see, e.g., the MACS, beyond-MACS, or SGAS-HST surveys, Ebeling et al. 2001, 2024; Sharon et al. 2020).

Enabled by its unique combination of high-resolution and wide-area survey capabilities, Euclid is poised to revolutionise the field of strong lensing by galaxy clusters. Although it is

scheduled to ultimately survey in the optical and near-infrared approximately $14\,000\,\text{deg}^2$ of the sky (Euclid Collaboration: Mellier et al. 2024), the Euclid Quick Release Q1 (2025) already holds immense potential to contribute significantly to the scientific goals outlined above. The Q1 dataset (Euclid Collaboration: Aussel et al. 2025; Euclid Collaboration: McCracken et al. 2025; Euclid Collaboration: Polenta et al. 2025; Euclid Collaboration: Romelli et al. 2025; Euclid Collaboration: Tucci et al. 2025; Euclid Collaboration: Copin et al. 2025; Euclid Collaboration: Le Brun et al. 2025; Euclid Collaboration: Paterson et al. in prep.) encompasses the three Euclid Deep Fields (EDFs), covering a total area of 63.1 deg^2 to the depth of the Euclid Wide Survey (EWS, Euclid Collaboration: Scaramella et al. 2022).

This potential is exemplified by the first results from Euclid's Early Release Observations (Cuillandre et al. 2024) of two lensing galaxy clusters, Abell 2390 and Abell 2764 (Atek et al. 2024, Abriola et al. in prep.; Diego et al. in prep.). These studies highlight Euclid ability to map the total mass distribution of such systems and to identify candidate high-redshift (z > 6) dropout sources (see also Weaver et al. 2024). By opening a broader discovery window and providing a platform for validating detection and analysis techniques, the Q1 release marks an exciting milestone in the mission's scientific journey.

This work aims to investigate Euclid's sheer potential to uncover lensing galaxy clusters and build the first catalogue of cluster-scale strong-lensing features and giant arcs in Euclid. This effort is crucially needed to generate efficient training sets for sophisticated machine-learning algorithms to be applied to the Euclid imaging data in the Data Release 1 (DR1) and beyond (e.g., Bazzanini et al. in prep.), where analyses based on visual inspections alone will be extremely challenging. To achieve these goals, we perform the first systematic visual inspection in the Q1 data, over an effective area of 4.4 deg², about 10% of Q1, and study the prevalence of strong-lensing clusters in

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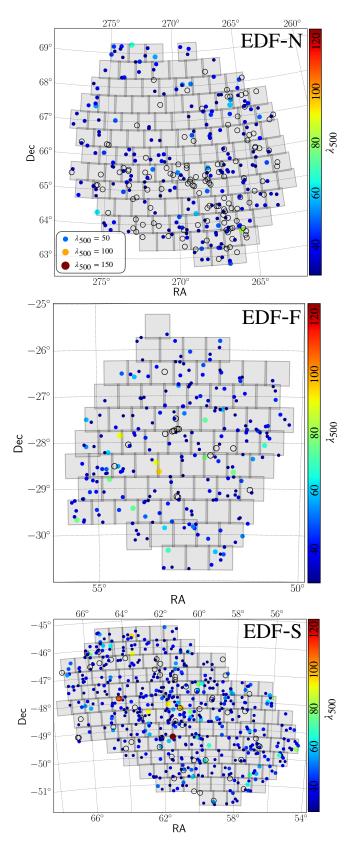


Fig. 1. Spatial distribution of galaxy clusters in the DLS and GCWG samples (see Sect. 3.1). From top to bottom: three zoomed-in views of the Euclid Deep Field North (EDF-N), Euclid Deep Field Fornax (EDF-F), and Euclid Deep Field South (EDF-S) regions. Dot colours and sizes are scaled according to cluster richness, while empty circles mark clusters for which the richness value is not measured by Wen & Han (2024). A cut in richness at $\lambda_{500} > 30$ is applied to the catalogue by Wen & Han (2024) to select the galaxy clusters for visual inspection.

an optically-selected sample of galaxy clusters based on richness. Given the large areas to be examined, we exploit the tool galaxyvote developed by Meneghetti et al. (in prep.), which allows inspectors to efficiently scrutinise and go through large samples of images, with functionalities that are equally powerful to search for galaxy-, group-, and cluster-scale lenses.

This paper is organised as follows. In Sect. 2, we concisely describe the *Euclid* imaging data and the creation of colour images of the candidate lensing galaxy clusters. Section 3 provides an overview of the considered galaxy cluster catalogue, the properties and capabilities of the newly developed tool, galaxyvote, and the adopted methodology for the visual inspection. Our results are presented and discussed in Sect. 4. Finally, we draw our conclusions in Sect. 5. Throughout the paper, we assume a flat Λ CDM cosmology with $H_0 = 70 \text{ km s}^{-1} \text{ Mpc}^{-1}$, and matter density $\Omega_m = 0.3$. Magnitudes are given in the AB system (Oke 1974). Statistical uncertainties are quoted as the 68% confidence levels.

2. Data and colour image generation

All the results presented in this work are based on the Euclid observations in the $I_{\rm E}$, $Y_{\rm E}$, $J_{\rm E}$, and $H_{\rm E}$ photometric filters (Euclid Collaboration: Cropper et al. 2024; Euclid Collaboration: Jahnke et al. 2024) from the Q1 data release, which covers a total sky area of approximately 63.1 deg², corresponding to the combined areas of the three EDFs (see Fig. 1, EDF-N 22.9 deg², EDF-F 12.1 deg², and EDF-S 28.1 deg²) but observed at the depth of the Euclid Wide Survey (EWS). For the $I_{\rm E}$ filter, this corresponds to a signal-to-noise ratio $S/N \ge 10$ for extended sources with a full width at half maximum (FWHM) of 0".3 and AB magnitude of 24.5 within an aperture with a diameter of 1".3. Instead, the observations in the near-IR bands reach a $S/N \ge 5$ for point sources with AB magnitude of 24.0 (Euclid Collaboration: Mellier et al. 2024). The $I_{\rm E}$, $Y_{\rm E}$, $J_{\rm E}$, and $H_{\rm E}$ images have a spatial sampling of 0".1 per pixel, equivalent to the native pixel scale of the $I_{\rm E}$ images, and a point-spread function of 0".13, 0".33, 0".35, and 0".36 FWHM, respectively (Euclid Collaboration: Mellier et al. 2024; Laureijs et al. 2011). We note that although the original spatial sampling of the $Y_{\rm E}$, $J_{\rm E}$, and $H_{\rm E}$ images is 0".3 per pixel, it is oversampled to match the $I_{\rm E}$ pixel scale by the *Euclid* data-reduction pipeline.

We create colour images by combining the *Euclid* observations in different bands using the following method. To begin, we use the STIFF software (Bertin 2012) to create colour images in the Red-Green-Blue (RGB) colour space. Specifically, we use the H_E , Y_E , and I_E bands for the red, green, and blue channels, respectively. We use the automatic sky background intensity and colour balance implemented in STIFF. At the same time, we manually adjust the contrast and brightness to provide satisfactory visibility for low-surface-brightness sources.

The spatial resolution of these images is penalised by the equal weight given to the $I_{\rm E}$ and near-IR bands. To improve the perceived spatial resolution, we perform a two-step image manipulation. First, we map the images from the RGB to the CIELAB colour space. The latter expresses colour as three values: *L* for perceptual lightness, and *a* and *b* for the four unique colours of human vision, red, green, blue, and yellow. Then, we substitute the *L* channel with the image in the $I_{\rm E}$ band. Finally, we map the image back to RGB colour space. The images are saved in the well-known Tag Image File Format (TIF).

This process results in images whose spatial resolution is driven by the $I_{\rm E}$ band, while the colour information is retained from the combination of $H_{\rm E}$, $Y_{\rm E}$, and $I_{\rm E}$ observations. Thus, the

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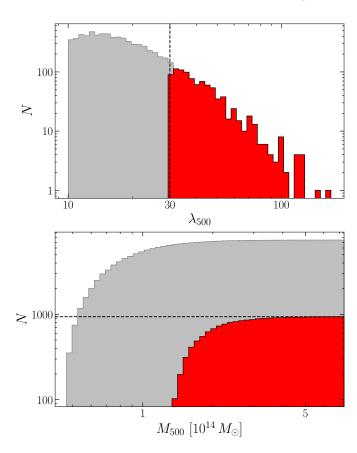


Fig. 2. Richness and mass distributions of galaxy clusters in Q1 from the catalogue by Wen & Han (2024). The top panel shows the distribution of cluster richness values (λ_{500}), while the bottom panel presents the cumulative distribution of cluster total masses (M_{500}). Grey histograms represent the galaxy clusters in Q1 detected in the DESI Legacy Imaging Surveys by Wen & Han (2024), whereas the red distributions correspond to the 939 clusters with $\lambda_{500} > 30$.

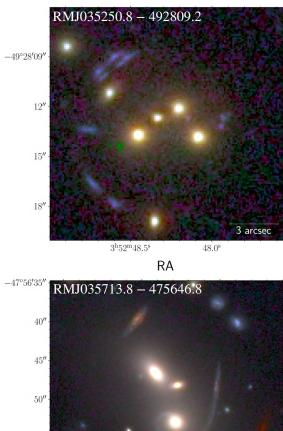
visibility of small-scale morphological features in the sources is greatly enhanced. For example, compact star-forming regions in distant galaxies are much better resolved in the $I_{\rm E}$ than in the near-IR bands and, therefore, they are more clearly visible in the colour images created with the procedure outlined above than in the RGB image initially created with STIFF.

It is important to note that the methodology employed to prepare the colour images is often used in astrophotography for visualisation purposes only. These images are unsuitable for scientific analysis (e.g., to perform multi-band photometry or measure photometric redshifts). However, the purpose of our experiment is to identify strong lensing features visually. This task is facilitated by the higher resolution and colour contrast achieved with the image processing that we have outlined. An additional caveat is that using the I_E band for the lightness channel dims the features only visible in the near-IR bands. For example, I_E -dropout sources appear strongly attenuated in our colour images.

3. Methodology

In this section, we describe the sample of visually-inspected candidate lens galaxy clusters (hereafter, the VI catalogue), which is created by combining two main galaxy cluster catalogues (see Sect. 3.1). Section 3.2 presents the new visual inspection tool, purposely built for this project. The visual inspection methodology is detailed in Sect. 3.3.

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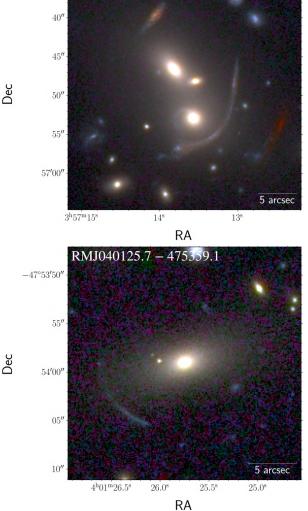


Fig. 3. The three secure galaxy cluster strong gravitational lenses $(\mathcal{P}_{\text{lens}} = 1)$ identified in the calibration phase (GCWG sample).

3.1. Galaxy cluster catalogue

To carry out the proposed experiment, we first considered the galaxy cluster catalogue presented by Wen & Han (2024), based on multi-band photometry from the DESI Legacy Imaging Sur-

veys Data Release (DR) 9 and 10 (Dey et al. 2019), and the Wide-field Infrared Survey Explorer (WISE, Wright et al. 2010). In summary, four optical bands (g, r, i, and z) and two midinfrared bands (W1 and W2) were used. The photometric information was complemented with available spectroscopy from the Two Micron All-Sky Survey (2MASS, Huchra et al. 2012), the Sloan Digital Sky Survey DR17 (SDSS DR17, Abdurro'uf et al. 2022), and the Dark Energy Spectroscopic Instrument Early Data Release (DESI EDR, DESI Collaboration et al. 2024). Galaxy clusters were identified as overdensities of stellar mass in cluster galaxies centred on the brightest cluster galaxy (BCG) candidates within a redshift bin of $\Delta z = 0.04 (1 + z)$ for $z \le 0.7$ or $\Delta z = 0.15 z - 0.037$ for z > 0.7. BCGs are identified based on their rzW1 magnitudes, estimated redshift values, and measured stellar masses $M_* \ge 10^{11} M_{\odot}$. The publicly available catalogue lists about 1.58 million candidate galaxy clusters, of which 7446 are located within the Q1 footprint. We then applied a cut in richness $\lambda_{500} > 30$, resulting in 939 galaxy clusters (hereafter, DLS galaxy clusters). As shown in Fig. 2, this is equivalent to applying a cut of $M_{500} \gtrsim 1.36 \times 10^{14} M_{\odot}$. The spatial distribution of the DLS galaxy clusters in the three Q1 fields is shown in Fig. 1, colour-coded according to the estimated value of λ_{500} by Wen & Han (2024).

As discussed in Wen & Han (2024), while their photometric selection has good completeness (80% - 94%), depending on the survey considered for the comparison), some galaxy clusters are not identified. Thus, we complement the DLS galaxy cluster sample with a compilation created by merging 15 catalogues of known galaxy clusters (courtesy of Jean-Baptiste Melin, see also Euclid Collaboration: Bhargava et al. in prep.). In detail, it includes galaxy clusters visible in the Q1 and DR1 footprints from the following catalogues (the number of Q1 systems is given in parentheses): the Meta-Catalogue of the compiled properties of X-ray detected Clusters of galaxies (MCXC, Piffaretti et al. 2011; Sadibekova et al. 2024, 35 galaxy clusters); the extended ROentgen Survey with an Imaging Telescope Array (eROSITA) cluster catalogue (Bulbul et al. 2024; Kluge et al. 2024, 125 galaxy clusters); the Meta Catalogue of SZ clusters (MCSZ, see Euclid Collaboration: Bhargava et al. in prep., 28 galaxy clusters); the Combined Planck-RASS catalogue of X-ray-SZ sources (ComPRASS, Tarrío et al. 2019, six galaxy clusters); the Meta-Catalogue of Cluster Dispersions (MCCD, see Euclid Collaboration: Bhargava et al. in prep., two galaxy clusters); the RedMaPPer galaxy cluster catalogue from the Dark Energy Survey science verification data (RM DES, Rykoff et al. 2016; Abbott et al. 2020, 177 galaxy clusters); the catalogue of clusters of galaxies identified from the Sloan Digital Sky Survey by Wen et al. (2012, WHL SDSS, 142 galaxy clusters); the Abell catalogue of rich clusters (Abell 1958; Abell et al. 1989, 23 galaxy clusters); the MARD-Y3 catalogue (Klein et al. 2019, 19 galaxy clusters); the XMM CLuster Archive Super Survey catalogue (X-CLASS, Koulouridis et al. 2021, seven galaxy clusters); the PSZSPT catalogue (Melin et al. 2021, 10 galaxy clusters); the PSZ-MCMF catalogue of *Planck* clusters over the DES region (Hernández-Lang et al. 2023, seven galaxy clusters); the SPT-SZ MCMF cluster catalogue (Klein et al. 2024a, 13 galaxy clusters); the RASS-MCMF cluster catalogue (Klein et al. 2023, 44 galaxy clusters); and the ACT-DR5-MCMF galaxy cluster catalogue (Klein et al. 2024b, 21 clusters). From this sample, 484 unique galaxy clusters (i.e., those at least 1'.5 apart) fall within the Q1 footprint, of which 117 are not included in Wen & Han (2024). We label this sample as GCWG (galaxy cluster working group) sample. The spatial distribution of these galaxy clusters

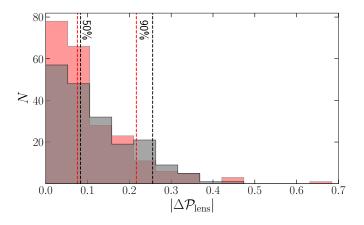


Fig. 4. Difference between the \mathcal{P}_{lens} values, $\Delta \mathcal{P}_{lens}$, attributed to the same clusters by different groups of inspectors and/or at different times. The black distribution shows the $\Delta \mathcal{P}_{lens}$ obtained for different occurrences of the same cluster in the GCWG sample during the calibration phase of the visual inspection. The red distribution refers to the $\Delta \mathcal{P}_{lens}$ attributed to the same cluster during the two phases of the visual inspection. The black and red dashed vertical lines mark the 50th and 90th percentiles of the \mathcal{P}_{lens} black and red distributions, respectively.

in the three Q1 fields, marked as empty black circles, is shown in Fig. 1.

In summary, to build the sample of galaxy clusters to be considered for visual inspection (the VI catalogue), we integrated the 939 DLS systems with the GCWG sample, resulting in a final catalogue of 1056 candidate lens clusters. Additionally, we removed 10 galaxy clusters from the DLS catalogue with projected separations smaller than 1.5. These occurrences are, in fact, not duplicate candidate galaxy clusters but systems lying angularly close but at different redshifts. Since the *Euclid* image cutouts adopted for the visual inspection have a size of $4' \times 4'$ (see Sect. 2), this entails that both systems are visually inspected within a single cutout. Finally, we excluded 220 galaxy clusters located close to the boundaries of the Q1 tiles, whose cutouts contain more than 50% of null values. The final number of cutouts to visually inspect is then equal to 826.

3.2. The galaxyvote platform

For the visual inspection of the *Euclid* images, we use the galaxyvote web application (Meneghetti et al. in prep.). In this section, we provide a short description of its functionalities.

The application back-end uses the Flask framework¹ to define routes (URLs) for the web application and associate them with Python functions. These functions are designed to interact with an application database. This is a relational database containing several tables. The software can handle multiple experiments using different image collections, providing access to many users, and managing assignments. Additional tables enable the storing of grades, comments, and even geometrical figures drawn by the users to mark specific regions of the images. The application front-end is based on HTML and JavaScript. It employs the Bootstrap CSS framework² to quickly and efficiently design and style responsive and modern web pages.

For a given visual inspection experiment, a configuration script allows us to initialise the application database, populating it with the list of images and authorised users. These users can

¹ https://flask.palletsprojects.com/en/stable/

² https://getbootstrap.com/

log in using pre-assigned credentials, accessing their dedicated workspaces. Administrators set the number of users to evaluate each image during the configuration. The system optimally creates the assignments based on the number of users and images. Each user's workspace contains a gallery of assigned images.

The users inspect the *Euclid* images through a web page containing the following features.

- An 800 × 800 pixel viewer allows the visualisation of the images. We use the javascript library OpenSeaDragon for smooth image navigation, including mouse-enabled zoom in and out functions. Users can opt to enter full-screen mode to improve their visualisation experience. To speed up the image panning and scrolling, we tile the images, converting them in the pyramidal Deep-Zoom-Image (DZI) format.³ OpenSeaDragon supports several image-serving protocols for tiled sources, including DZI.
- Basic filters, such as increasing and reducing contrast and brightness to enable users to improve the visibility of specific sources in the images. These filters are implemented using the OpenSeaDragonFiltering add-on.⁴
- A rectangle drawing tool. Users can enable drawing rectangles in the image viewer. They can draw multiple rectangles to mark the positions of interesting features in the image and save them into the database. For our experiment, we ask users to draw rectangles on gravitational arcs and arclets, and sets of multiple images of background sources.
- A voting panel. Users are asked to classify the inspected image. For our experiment, we set up three classes, namely: 'Certain Lens' (A), if the image contains any features that the user associates with a strong lensing effect with extremely high confidence; 'Probable Lens' (B) if the detected features lead the user to believe that there is a strong lensing effect, but with lower confidence; and 'No Lens' (C) if the user does not detect any strong lensing feature.
- A comment box. Users can leave feedback on their feature identifications. In particular, for our experiment, they were instructed to explain why they believed that strong lensing effects could explain the detected features. In addition, they could describe their identifications in more detail if they wanted.

3.3. The visual inspection

While the primary aim of this experiment is to uncover new lens galaxy clusters, all inspectors were instructed to vote for any strong-lensing feature, regardless of whether it occurs in galaxy-, group-, or cluster-scale systems. The team of inspectors comprised 44 members of the Euclid Consortium (hereafter referred to as 'experts' or 'inspectors'), approximately half of whom are specialists in strong lensing by galaxy clusters, and thus very familiar with cluster-scale strong lensing features.

The visual inspection experiment is divided in two stages, as described below. We note that the experts did not have access to information about the galaxy cluster's properties, such as coordinates, redshift, richness, or total mass, during the entire visual inspection process, thus ensuring a blind search for strong-lensing features.

The first stage consists of a 'calibration phase' in which the 44 inspectors were tasked to vote exclusively on a subsample of galaxy clusters contained in the GCWG sample (a total of

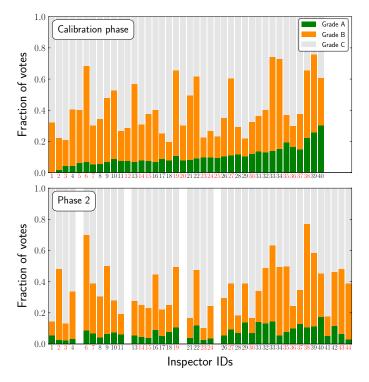


Fig. 5. Fraction of A, B, and C grades assigned by each inspector, identified by unique numerical IDs, to the candidate cluster lenses. The results from the calibration phase and from Phase 2 are shown in the upper and lower panels, respectively. Inspectors with little or no experience in strong gravitational lensing by galaxy clusters are marked with red IDs. Inspectors who graded less than two clusters are not included.

434 cutouts, see Sect. 3.1). This collection of candidates is large enough to train the inspectors for the second phase. In fact, the number of assignments for each inspector varied between 55 and 87 so that each cutout could receive seven votes. This number of votes was determined to be the optimal compromise between the total number of required votes and the need for a robust final grade (see e.g., Rojas et al. 2023; Schuldt et al. 2025). The primary aim of this phase is to train the inspectors in identifying cluster-scale lenses and to familiarise them with the visual inspection tool. Additionally, this phase allows for identifying possible software bugs while implementing feedback on potential improvements for the second, larger stage. We note that duplicate entries in the GCWG sample were not removed during this phase, allowing us to evaluate how the same object is ranked by different groups of inspectors or by the same inspector at different times. The calibration phase was completed by 40 out of the 44 experts involved, gathering 88% of the expected number of votes in about a week.

In contrast, the second stage examined the 826 *Euclid* images in the complete VI catalogue presented in Sect. 3.1. This phase involved 44 experts, of which 38 completed the inspection in about three weeks. Thus, we collected 90% of the expected grades. As in the calibration phase we aimed at collecting seven grades per image. The number of assignments per inspector varied between 113 and 163.

4. Results

In each phase, a probability value of being a strong gravitational lens, $\mathcal{P}_{\text{lens}}$, is assigned to each cluster. This probability is com-

³ https://shorturl.at/oZe52

⁴ https://github.com/usnistgov/OpenSeadragonFiltering

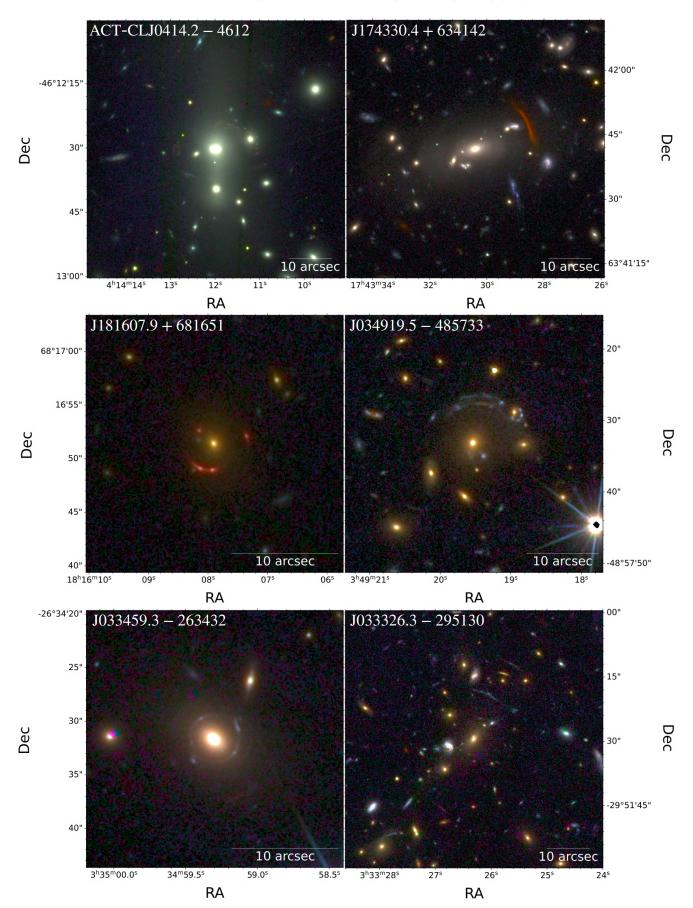


Fig. 6. Six out of the 13 secure galaxy cluster strong gravitational lenses ($\mathcal{P}_{\text{lens}} = 1$) identified in the Phase 2 run (VI catalogue). The remaining seven secure Phase 2 lenses are shown in Figs. 7, 8, and 3 (RMJ035713.8–475646.8 and RMJ040125.7–475359.1).

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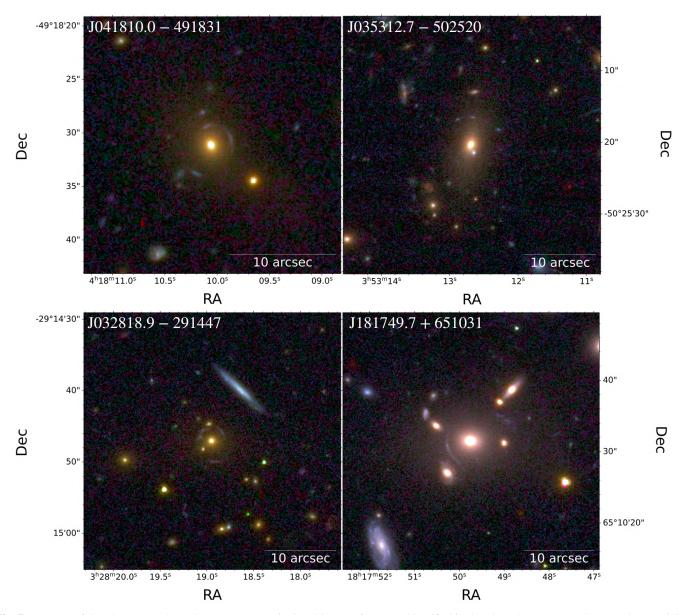


Fig. 7. Four out of the 13 secure galaxy cluster strong gravitational lenses ($P_{\text{lens}} = 1$) identified in the Phase 2 run (VI catalogue). The remaining nine secure Phase 2 lenses are shown in Figs. 6, 8, and 3 (RMJ035713.8–475646.8 and RMJ040125.7–475359.1).

Table 1. List of galaxy clusters in the calibration phase (GCWG sample) with a probability $\mathcal{P}_{lens} > 0.5$ of being a strong gravitational lens. For each galaxy cluster, we report the total number of A, B, and C grades (N_A , N_B , and N_C) assigned by the inspectors. The star (\star) and dagger (\dagger) symbols mark the gravitational lenses previously observed by the *Hubble* Space Telescope and *James Webb* Space Telescope, respectively. The catalogue is published in its entirety in machine-readable format. A portion listing the secure gravitational lenses ($\mathcal{P}_{lens} = 1$) is shown here for guidance regarding its form and content.

Name	RA	Dec	$N_{\rm A}$	$N_{\rm B}$	N _C	$\mathcal{P}_{\text{lens}}$
RMJ040125.7-475359.1	60 35721	-47.89974	4	0	0	1.00
RMJ035713.8–475646.8	59.30752	-47.94633	- 14	0	0	1.00
RMJ035250.8-492809.2	58.21182	-49.46921	6	0	0	1.00
	•••					

puted as

$$\mathcal{P}_{\text{lens}} = \frac{N_{\text{A}} + 0.5 N_{\text{B}}}{N_{\text{A}} + N_{\text{B}} + N_{\text{C}}},\tag{1}$$

=

ate the cluster as a secure gravitational lens (all A grades). On the contrary, a value of $\mathcal{P}_{\text{lens}} = 0.5$ indicates that all inspectors are uncertain about the presence of strong lensing features (all B grades) and/or that the number of A grades (secure presence of strong lensing features) is equal to the number of C

A value of $\mathcal{P}_{lens} = 1$ is assigned only if all inspectors evalu-

where N_A , N_B , and N_C are the numbers of A, B, and C grades given to the image, respectively.

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Table 2. List of galaxy clusters in the Phase 2 run (VI catalogue) ranked with a probability, $\mathcal{P}_{\text{lens}}$, greater than 0.5 to be strong gravitational lenses. For each galaxy cluster, we report the number of A, B, and C votes (N_A , N_B , and N_C) assigned by the inspectors. The star (\star) and dagger (\dagger) symbols mark the gravitational lenses previously observed by the *Hubble* Space Telescope and *James Webb* Space Telescope, respectively. The catalogue is published in its entirety in machine-readable format. A portion listing the secure gravitational lenses ($\mathcal{P}_{\text{lens}} = 1$) is shown here for guidance regarding its form and content.

Name	RA	Dec	$N_{\rm A}$	$N_{\rm B}$	N _C	$\mathcal{P}_{\text{lens}}$
ACT-CLJ0411.2-4819	62.80204	-48.31183	7	0	0	1.00
J174330.4+634142	265.87665	63.69491	7	0	0	1.00
ACT-CLJ0414.2-4612	63.55490	-46.20033	6	0	0	1.00
RMJ035713.8-475646.8	59.30752	-47.94633	6	0	0	1.00
J034919.5-485733	57.33133	-48.95924	6	0	0	1.00
J181749.7+651031	274.45724	65.17541	6	0	0	1.00
J181607.9+681651	274.03287	68.28094	6	0	0	1.00
J041810.0-491831	64.54186	-49.30865	6	0	0	1.00
J035312.7-502520	58.30281	-50.42233	7	0	0	1.00
J033326.3-295130	53.35960	-29.85820	7	0	0	1.00
RMJ040125.7-475359.1	60.35721	-47.89974	7	0	0	1.00
J033459.3-263432	53.74707	-26.57546	7	0	0	1.00
J032818.9-291447	52.07892	-29.24641	7	0	0	1.00

grades (secure absence of strong lensing features). In the following two sections, which describe the main results obtained from the two phases of the visual inspection, we consider clusters with $\mathcal{P}_{\text{lens}} > 0.5$ as potential strong gravitational lenses.

4.1. Calibration phase

The calibration phase returned 25 strong lensing clusters. They are listed in Table 1. In Fig. 3, we show the three cluster lenses with $\mathcal{P}_{\text{lens}} = 1$. As evident from the table, there are significant discrepancies in the total number of votes, $N = N_{\rm A} + N_{\rm B} + N_{\rm C}$, assigned to some of the clusters. For instance, the two clusters ACT-CLJ0411.2-4819 and RMJ040125.7-475359.1 have N equal to 49 and 4, respectively. As previously mentioned, these differences arise from the presence of 60 duplicate clusters that appear at least twice in the GCWG sample. Thus, their images received a larger number of grades than in the case of clusters without duplicates. To test the robustness and self-consistency of the visual inspection methodology, we plot the differences between the \mathcal{P}_{lens} values assigned to different occurrences of the same clusters as a grey histogram in Fig. 4. For more than 50% (90%) of the duplicates, the difference in $\mathcal{P}_{\text{lens}}$ is less than 0.09 (0.26). This analysis demonstrates that the strong lensing probability is only marginally affected by variations in the group of inspectors voting for a cluster or by an inspector's vote assigned to a cluster at different times. As an additional test, we present in Fig. 5, the percentage of A, B, and C votes assigned by each inspector to the visually inspected clusters. Inspectors with no prior experience in strong gravitational lensing by galaxy clusters are marked with red IDs on the horizontal axis. This analysis reveals the absence of any significant correlation between the number of votes and the users' level of expertise. The observed fluctuations are, in fact, consistent with the variance in number of cluster lenses within the cluster samples inspected by the users. The calibration phase did not reveal any major bugs in the visual inspection tool described in Sect. 3.2, which is therefore also adopted for the second phase.

4.2. Phase 2

In Table 2, we present the 76 strong gravitational lensing clusters identified during the second phase of visual inspection from the VI catalogue. In this phase, the inspectors identified 13 secure cluster lenses ($\mathcal{P}_{\text{lens}}=1$), four of which were already found in the calibration phase (two were classified as secure lenses in both phases, while the other two were ranked with $\mathcal{P}_{\text{lens}}=0.99$ and $\mathcal{P}_{\text{lens}}=0.83$ in the calibration phase). However, the galaxy cluster RMJ035250.8–492809.2, identified as a secure lens in the first phase, is absent from the VI catalogue due to the richness cut of $\lambda_{500} > 30$ applied during its creation. Specifically, Wen & Han (2024) estimated a richness value of $\lambda_{500} = 28.61$ for this cluster. In Figs. 6, 7, and 8, we show the additional 11 secure cluster lenses identified in the second phase.

Since 211 of the galaxy clusters visually inspected in the calibration phase were also re-inspected in the Phase 2, we show the absolute differences between the \mathcal{P}_{lens} values assigned to the same clusters in the two phases as a red histogram in Fig. 4. This additional test demonstrates that most clusters were consistently ranked between the two visual inspection phases. Specifically, 90% of the analysed objects exhibit \mathcal{P}_{lens} differences of less than 0.22. Similarly to the calibration phase, in Fig. 5 we present the percentage of A, B, and C votes assigned to the clusters visually inspected by each user. As in the calibration phase, Phase 2 also does not reveal any significant bias in the distribution of votes across the sample of inspectors or as a function of user expertise.

4.3. Characterisation of the physical properties of the lens clusters

Although a detailed study of the physical properties of the newly observed galaxy cluster strong gravitational lenses is beyond the scope of this work, we present some preliminary results from our analysis in this section. In Fig. 9, we plot the distribution of M_{500} cluster masses as a function of redshift. The markers representing the visually inspected clusters are colour-coded according to their $\mathcal{P}_{\text{lens}}$ values. The figure reveals that most galaxy cluster lenses are in the redshift range 0.32 < z < 0.68. This result can be attributed to a combination of two main factors. On

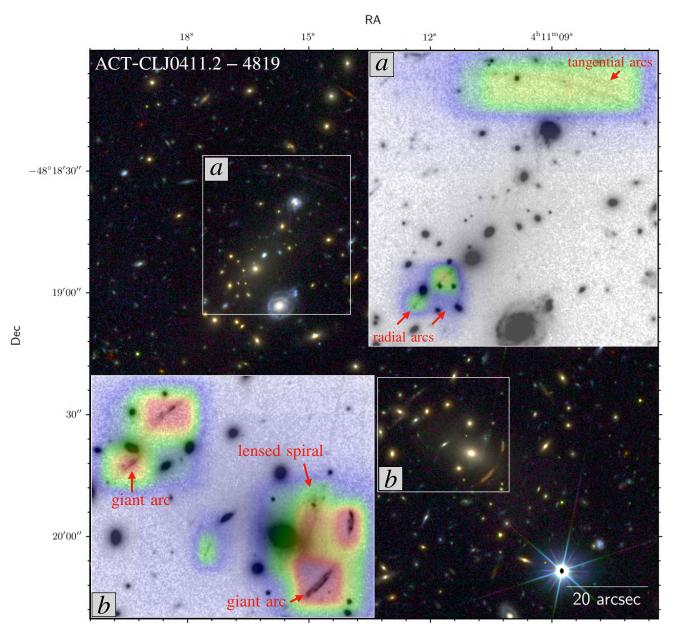


Fig. 8. Merging galaxy cluster identified as a secure gravitational lens in the second phase of the visual inspection. The zoom-ins centred on the two merging massive structures are superimposed, showing heat maps derived from the rectangular regions drawn by the inspectors during the visual inspection process. These maps highlight various strong lensing features, including tangential and radial arcs, as well as multiple images, with redder colours indicating more evident features.

the one hand, the wavelength coverage of the *Euclid* photometric filters, the EWS image depth, and the higher resolution of the $I_{\rm E}$ band compared to the near-IR bands are designed to facilitate the identification of most of the galaxies at z < 2. On the other hand, as shown by Meneghetti et al. (2013, see also Meneghetti et al. 2023) using cosmological simulations, the lensing cross-section for giant arcs for sources at that redshift is maximised for cluster lenses at $z \simeq 0.3$.

Based on our census of galaxy cluster strong gravitational lenses identified in the 63.1 deg² covered by EDF-N, EDF-S, and EDF-F, we can provide an immediate estimate of the expected number density of cluster lenses per square degree detectable in the EWS. In Fig. 10, we show the inverse cumulative distribution of the number density of cluster lenses as a function of the lensing probability. Specifically, we expect approximately 0.3 deg⁻² cluster lenses with $\mathcal{P}_{\text{lens}} > 0.9$. By lowering the lensing proba-

bility threshold to $\mathcal{P}_{\text{lens}} > 0.5$, the expected number density of cluster lenses increases to 1.2 deg^{-2} . Given the final EWS sky coverage of approximately $14\,000 \text{ deg}^2$, we predict that *Euclid* will detect more than 4200 cluster lenses exhibiting unequivocal evidence of extended, bright giant arcs and multiple images. It is important to note that these estimates are likely conservative, since they do not account for newly discovered cluster lenses that are not included in existing catalogues.

In Fig. 8, we show as an example the rectangles drawn by the inspectors in the field of ACT-CLJ0411.2–4819, highlighting the strong lensing features they identified. The red pixels, corresponding to regions where many rectangles overlap, indicate areas of the clusters that contain prominent giant arcs and multiple images. These rectangles will provide the sample to train deep-learning models to find similar features automatically in future *Euclid* data.

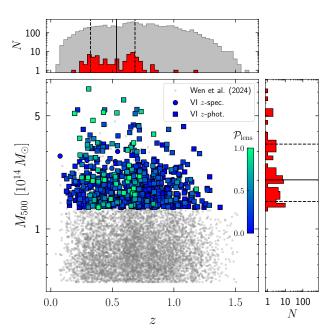


Fig. 9. Total mass-redshift distribution of the clusters visually inspected during the Phase 2 run. Small grey dots and grey histograms refer to the galaxy clusters detected in the DESI Legacy Imaging Surveys by Wen & Han (2024) and located within the Q1 63.1 deg² area. The squares and dots correspond, respectively, to the galaxy clusters with measured photometric or spectroscopic redshifts, colour-coded according to the lensing probability, $\mathcal{P}_{\text{lens}}$. The total mass and redshift distributions of the galaxy clusters with $\mathcal{P}_{\text{lens}} > 0.5$ are shown as red histograms, while the black lines represent the 16th (dashed line), 50th (solid line), and 84th (dashed line) percentiles of these distributions. The effect of the selection criterion ($\lambda_{500} > 30$) adopted to select the galaxy clusters for the visual inspection is clearly visible.

Among the secure cluster lenses detected in Q1, the cluster identified as ACT-CLJ0411.2–4819, shown in Fig. 8, deserves special mention. This is a merging cluster that exhibits a variety of bright and extended strong lensing features, including tangential and radial giant arcs at different redshifts. Additionally, several smaller galaxy groups surrounding the main cluster, each displaying evident strong lensing features, make this cluster an excellent candidate for future follow-up observations.

Finally, we also identified several galaxy-galaxy strong lensing events in cluster fields. This is expected since the dense galaxy cluster environments enhance the strong lensing cross section of galaxies in these fields (e.g., Meneghetti et al. 2020).

5. Conclusions

We have presented the first catalogue of strong lensing galaxy clusters observed by *Euclid*. These clusters were part of the catalogue of optically-selected galaxy clusters by Wen & Han (2024) supplemented with other clusters. Most of them were observed from space for the first time, thanks to *Euclid*. For this reason, only a few of these galaxy clusters were known to host some strong lensing features. Thanks to the spatial resolution and depth of *Euclid* observations, we identified several gravitational arcs and multiple images of galaxies in the cluster backgrounds.

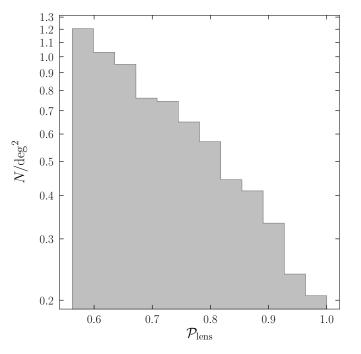
To find these features and classify clusters as lenses and nonlenses, we visually inspected colour images created by combin-

Fig. 10. Inverse cumulative distribution of the galaxy cluster number density as a function of the lensing probability, \mathcal{P}_{lens} , assigned during the second phase of the visual inspection process.

ing the *Euclid* observations in the $I_{\rm E}$, $Y_{\rm E}$, and $H_{\rm E}$ bands. The search was blindly carried out by 44 inspectors using a new interactive visualisation tool. We found 83 strong gravitational lenses among over a thousand inspected clusters, 14 of which exhibit secure strong lensing features such as tangential and radial arcs and multiple images. To our knowledge, only two arcs among those we have found had been previously identified in groundbased observations (the brightest arcs in J174330.4+634142, a.k.a. A2280, and ACT-CLJ0411.2-4819 Gioia et al. 1995; Bayliss et al. 2016). Only three of the identified gravitational lenses, marked with stars (\star) in Tables 1 and 2, had been previously observed by the Hubble Space Telescope, with one of them, marked with a dagger (†), also observed by the James Webb Space Telescope. For the remaining 80 lenses, Euclid has provided the first space-based optical observations and the spatial resolution necessary to discover many more strong lensing features. Considering the number of newly observed lensing galaxy clusters and the high quality of *Euclid* imaging data, even at the depth of the EWS, *Euclid* will increase the sample of known gravitational lenses by more than one order of magnitude, paving the way for an unprecedented advancement in the field of gravitational lensing by galaxy clusters.

In the sample we have inspected, we found that around 0.3 clusters per square degree contain evident strong lensing features. Based on this number density, we expect that *Euclid* will observe more than 4200 strong lensing clusters in the EWS, assuming optical selection above a minimum richness of 30. This estimate is consistent with the forecasts of Boldrin et al. (2016), based on simulations in the Λ CDM cosmological model, although the impact of the selection function needs to be studied in more detail.

The redshift distribution of the strong lensing clusters in our sample peaks at $z \approx 0.5$, also consistent with expectations (e.g., Boldrin et al. 2012; Meneghetti et al. 2013; Boldrin et al. 2016). Based on the galaxy distributions, the sample does not appear to



be biased in terms of cluster dynamical state. Few lenses show elongated or multimodal spatial distributions of galaxies that are likely cluster members. Other lenses have more axially symmetric distributions of cluster galaxies.

Soon, we expect to find more strong lensing clusters in the upcoming *Euclid* data. These observations will enable many new studies based on strong gravitational lensing, aimed at understanding the nature of dark matter and dark energy, constraining cosmological parameters, studying high-redshift sources, and more. For many of these lensing applications, combining the *Euclid* data with complementary observations, including spectroscopy and observations in the X-ray, submillimetre, and radio domains will be crucial. Exploiting the synergy between *Euclid* and optical time-domain surveys, in particular the Vera C. Rubin Observatory's Legacy Survey of Space and Time (Guy et al. 2022), will also enable discovery of explosive transients that are gravitationally lensed by the strong lensing galaxy clusters.

Euclid is accumulating data at around 6.25 deg^2 per day. The fast data volume growth makes our visual inspection approach inefficient in searching for strong lenses. Given that the Phase 2 run took approximately three weeks to be completed, we estimate that visually inspecting the entire EWS area, 260 times larger than the Q1 area, would require more than 15 years. As seen in searches for galaxy-galaxy strong lenses, citizen science may help mitigate this problem (Euclid Collaboration: Walmsley et al. 2025; Euclid Collaboration: Holloway et al. 2025). However, despite being less numerous, galaxy clusters are much more complex lenses than galaxies. They produce a variety of image configurations that inspectors cannot easily recognise without proper training. For this reason, automating the search for strong lensing features in galaxy clusters is a priority. In this work, we identified several tens of gravitational arcs and arclets. We will combine them with simulated data to train algorithms based on deep learning, such as different architectures of convolutional neural networks, to find features like gravitational arcs, arclets, and multiple images.

Our work demonstrates the huge potential of the *Euclid* mission for discovering new strong lensing clusters. We identified several lenses with multiple gravitational arcs, implying large strong lensing cross-sections. These galaxy clusters will be reobserved by *Euclid* multiple times during the course of the mission as part of the EDF survey. These future observations will allow us to find additional arcs and multiple images by reaching fainter magnitude limits. Thus, we will collect many more observables to build robust total mass models of these lenses. In addition, by comparing observations taken at different times, we may be able to detect lensed transients. The observations of such sources would enable further science cases. For example, in the case of multiply imaged time-variable sources, it may be possible to measure the cosmic expansion rate (Kelly et al. 2015, 2016; Grillo et al. 2015, 2018, 2024).

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